## **T6 GNSS Receiver**



T6 is designed to enhance your performance in the field survey and to provide the most reliable positioning result.

It integrates a 1598 channels world leading GNSS positioning engine, a high precision IMU, a patented-designed Farlink UHF radio, and 4G, Bluetooth, wifi... all state-of-art technologies are there to ensure you an excellent working experience.



# **Key Features**

#### **Quick and Reliable Fixed Solution**

With the high-gain GNSS antenna of our latest design in 2025, the usability of Glonass & Galileo satellites is greatly improved, so even in harsh environment T6 still is able to track more satellite than other receivers and deliver centimeter accuracy positioning result in few seconds.

### Work Anytime, Anywhere with L-Band

By receiving correction delivered directly from L-band satellites, T6 allows you to achieve 10 to 20 centimeter-level accuracy with only one rover on hand when base receiver or CORS service is not accessible in remote areas. This function is based on Galileo HAS and BDS PPP, please apply the registration code from local distributors.

# **Powerful and Durable Radio Connectivity**

T6 features our patented-designed Farlink radio technology. When it works as an UHF base station T6 is able to transmit correction data farther than others, in good condition the working range can be 10 to 15 km. In 2025, the latest protocol Farlink Pro is added as a new option, for user to cope with challenging environment.

# **Efficient IMU Tilt Survey**

T6's IMU sensor is almost all-time available. When surveyor rotate the pole while walking, or changing the attitude of the receiver, the availability status won't be easily lost. The IMU is calibrate-free.

## **Superior Endurance & Ruggedness**

The newly developed power management system allows T6 to work up to 15-18 hours as rover and can be recharged by a type-C connector.

The shock-resistant frame, water-proof frame all have been enhanced, now the overall proof level is IP68.



### **SPECIFICATIONS**

GNSS Features		Communications	
Channels	1598	I/O Port	4G SIM Card Slot
GPS	L1, L1C, L1C/A, L2C, L2P(Y), L5	,	5-PIN LEMO interface (external power port + RS232
GLONASS	G1, G2, G3	-	Type-C interface
BDS	B1I, B2I, B3I, B1C, B2a, B2b	-	(charge + OTG+ Ethernet)
GALILEO	E1, E5a, E5b, E6, AltBOC*	-	UHF antenna interface
SBAS	L1*	Internal UHF	Radio receiver and transmitter, repeater function
IRNSS	L5*	Frequency Range	410-470MHz
QZSS	L1, L2C, L5*	Communication Protocol	Farlink, Farlink Pro, Trimtalk, SOUTH, Satel
MSS L-Band*	BDS PPP & Galileo HAS	Communication Range	Typically 5-8km with Farlink protocol, up to 15km
Positioning Output Rate	1Hz~20Hz	Bluetooth	Bluetooth 3.0/4.1 standard, Bluetooth 2.1 + EDR
Initialization Time	< 10s	NFC Communication	Support
Initialization Reliability	>99.99%	Modem	802.11 b/g/n standard
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Positioning Precision		Data Storage/Transmission	
	Horizontal: 0.25 m + 1 ppm RMS	Storage	4GB SSD internal storage, extendable up to 64GB
GNSS Static  Static (Long Observation)	Vertical: 0.50 m + 1 ppm RMS	Data transmission  Data format	Support external USB storage (OTG)
	Horizontal: 2.5 mm + 0.5 ppm RMS		The customizable sample interval is up to 20Hz
	Vertical: 3.5 mm + 0.5 ppm RMS		Plug and play mode of USB data transmission
	Horizontal: 2.5 mm + 0.1 ppm RMS		Supports FTP/HTTP data download
	Vertical: 3 mm + 0.4 ppm RMS		Static data format: STH, Rinex2.01, Rinex3.02 and
Rapid Static PPK	Horizontal: 2.5 mm + 0.5 ppm RMS		etc.
	Vertical: 5 mm + 0.5 ppm RMS		Differential data format: RTCM 2.1, RTCM 2.3,
	Horizontal: 3 mm + 1 ppm RMS	-	RTCM 3.0, RTCM 3.1, RTCM 3.2
	Vertical: 5 mm + 1 ppm RMS		GPS output data format: NMEA 0183, PJK plane
RTK(UHF)	Horizontal: 8 mm + 1 ppm RMS		coordinate, Binary code
MMOIII)	Vertical: 15 mm + 1 ppm RMS		Network model support: VRS, FKP, MAC, fully
RTK(NTRIP)	Horizontal: 8 mm + 0.5 ppm RMS	-	support NTRIP protocol
	Vertical: 15 mm + 0.5 ppm RMS		Support William protocor
SBAS Positioning	Typically<5m 3DRMS	Sensors	
RTK Initialization Time	2~8s	IMU	Built-in IMU module, calibration-free, 60°
IMU Tilt Angle	0°~60°	Electronic bubble	Controller software can display electronic bubble,
INTO THE THISIC	0 00	Electronic subsite	checking leveling status of the carbon pole in
Hardware Performance			real-time
Dimension	135mm(W) ×135mm(L) × 83mm(H)	Thermometer	Built-in thermometer sensor, adopting intelligent
Weight	900g (battery included)	memorie	temperature control technology, monitoring and
Material	Magnesium aluminum alloy shell		adjusting the receiver temperature
Operating Temperature	-45°C~+75°C		adjusting the receiver temperature
Storage Temperature	-55°C~+85°C	User Interaction	
Humidity	100% Non-condensing	Operating system	Linux
Waterproof/Dustproof	IP68 standard, protected from long time	Buttons	Single button
	immersion to depth of 1m	Indicators	Bluetooth, satellites, data, charging and power
	IP68 standard, fully protected against	indicators	indicators
	blowing dust	Web interaction	With access to Web UI via WiFi or USB connection,
Shock/Vibration	Withstand 2 meters pole drop onto the		users can monitor the receiver status and change the
	cement ground naturally		configurations
Power Supply	6-28V DC, overvoltage protection	Voice guidance	Chinese/English/Korean/Spanish/Portuguese/Russian
Battery	7.2V, 6800mAh rechargeable Lithium-ion	- Siec Baidariec	/Turkish/French/Italian
- Lactory	battery	Secondary development	Provides secondary development package, and opens
	Nation y	occoridary development	
Rattery Life	15h (rover bluetooth mode)		the OpenSIC observation data format and interaction
Battery Life	15h (rover bluetooth mode)		the OpenSIC observation data format and interaction interface definition
*Reserve for future upgrade.		Cloud service	interface definition
*Reserve for future upgrade. Remarks: Measurement accuracy ar	15h (rover bluetooth mode)  d operation range might vary due to atmospheric titions, observation time, temperature, signal geometry	Cloud service	· ·



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