

MODEL



M20



M10

PHYSIC/	٨L
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Dimension (LxWxH) 1180x700x390 mm 950x500x350 mm 12.8KG (without battery) Weight 6Kg (without battery) mini Single-frequency Echo Sounder (default), plus ADCP, Sub-bottom Profiler, Side Scan Sonar, Multi-beam Echo Sounder, etc. mini Single-frequency Echo Payload Sounder (default) only

Nano carbon fiber polymer composite Material

IP Rating **IP67**

Beaufort Scale: Resistant to Cat 3 winds, Cat 2 waves Wind-wave Resistance

Nano SIM card slot available Telecom Interface

Modular, simple assembly and usage process, no need for complex tools System Assembly

ELECTRICAL

Video Communication 4G telecom & network bridge

High-efficiency culvert long-life brushless motor Motor Engine

Typical 850W each Motor Power

Portable and detachable high-performance ternary Lithium battery, 33V, 50AH Battery

> 5.5 hrs @2m/s 7 hrs @2m/s

> > single battery, long-life option available

PERFORMANCE

Endurance

Propulsion Electric drive 7m/s max. Cruise Speed

Steering engine free, differential steering, reversible Steering Mode

Built in, highly integrated with transducer, fully automatic operation after power Default Echo Sounder connection. Operating frequency 200kHz, beam angle 5°, sounding angle 0.15-100m (upgradeable). ±1cm±0.1%D (D is the depth value)

Operating frequency - high frequency≥200kHz, low frequency≤20kHz; beam angle - high frequency≤5° Optional Echo Sounder

low frequency≤20°; sounding angle high frequency 0.15-300m, low frequency 0.5-600m 200 kHz: ±1cm±0.1%D (D is the depth value) 33 kHz: ±10cm±0.1%D (D is the depth value) N/A

POSITIONING

IMU Onboard

Dual antenna, pre-installed in front and rear individually **GNSS Antenna**

GPS:L1C/A,L2P,L2C,L5; BDS:B1I,B1C,B2a,B2b,B2I,B3I; GLO:G1,G2,G3*; GAL:E1,E5b,E5a,E5 AltBoC*,E6c*;QZSS*:L1C/A,L2C,L5;SBAS*:L1C/A,L5;IRNSS*:L5 **GNSS Constellation**

RTK Accuracy H:±(8+106 xD)mmV:±(15+106xD)mmD-Baseline length (Unit: mm)

Supports GNSS-inertial, 1PPS, IMU refresh rate 200Hz max.

Heading accuracy 0.15°@1m baseline, orientation accuracy 0.25°@1m baseline IMU Performance

REMOTE CONTROL

Maximum 2.5KM **Connection Distance**

7.2-inch high-definition screen display, real-time control of USV movement, set the working mode, view the image in front of the USV

Note: all information above is subject to change without any prior notice.

SANDING OPTIC-ELECTRICS INSTRUMENT CO.,LTD Add: 7/F, No.39 Si Cheng Road, Tian He IBD Guangzhou 510663, China Tel: +86-20-23380888 Fax: +86-20-23380800 E-mail:export@sandinginstrument.com http://www.sandinginstrument.com



AQUAM20/M10 Built for Marine Unmanned



ILLUSTRATION 📥



- 1 Dual Ducted Propeller double propulsion system for powerful cruise
- 2 Double-decker Trimaran smart structural design for reliable and stable cruise
- 3 Rear GNSS Antenna works with inbuilt GNSS for precise positioning
- 4 Auto-pilot System excels in unmanned operation
- 5 Network Bridge Antenna Port talks with remote controller to transfer data
- 6 Specialized Moon Pool ready to fit a variety of payloads like ADCP, multi-beam
- 7 4G Telecom Antenna Port equipped for RTK corrections and vessel remote control
- 8 Radio Datalink Antenna Port communicates with base station for RTK corrections
- 9 Battery Compartment endurance around 5 hours in auto-pilot mode
- 10 Power Display Panel for direct voltage value reading
- 11 Device Power Switch one-key quick start
- 12 Recharge Port standalone or direct onboard charging, optional
- 13 Mini Echo Sounder F18S single frequency, built in as default
- 14 Double-sided Guide Light blinks in green against mission safety
- 15 World-famous 360° Camera provides pano view during missions
- 16 Millimeter Microwave Radar designed for obstacle avoidance
- 17 Front GNSS Antenna provides stable heading info for auto-pilot
- 18 Remote Control Unit mission planning and control all in one



SOFTWARE

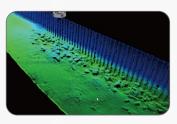
APPLICATIONS



Auto-pilot



Satellite Map



Multi-beam Mapping



Obstacle Detection



Dredging Works



Underwater Bathymetry

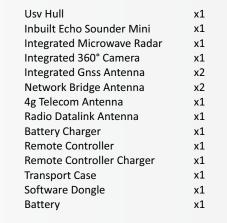


River Measurement



Hydrology Investigation

CONFIGURATION C



Note: just take M20 for example above.





